

Midterm Examination
February 26, 2019

1. Dynamic Behavior and Stability of a Pendulum with Drag

Consider a simple model of a rigid pendulum moving in an atmosphere with non-negligible drag. The model describing the motion of the pendulum is given by

$$\frac{d^2\theta}{dt^2} = \frac{1}{m\ell} \left(-mgsin(\theta) - \frac{1}{2}\rho\ell \frac{d\theta}{dt} C_D A \right)$$

where θ is the angle in radians defined as the deviation from normal, m is the mass of the pendulum, ℓ is the length of the pendulum, g is acceleration due to gravity, ρ is the density of the medium in which the pendulum swings, C_D is the drag coefficient, A is the cross-sectional area of the pendulum, and t is time.

Consider the following numerical parameters, $m = 1.0$ kg, $\ell = 1.0$ m, $g = 9.8$ m/s², $\rho_{vacuum} = 0.0$ kg/m³, $\rho_{air} = 1.225$ kg/m³, $\rho_{water} = 1000.0$ kg/m³, $A = 0.01$ m² and $C_D = 0.47$.

For parts (a) through (f) of the problem, consider the following initial conditions, at time $t = 0$,

$$\theta = \frac{\pi}{2} \quad \text{and} \quad \frac{d\theta}{dt} = 0.$$

- (a) Is this ODE linear or nonlinear?
- (b) Convert the second order ODE to a system of first order ODEs.
- (c) Numerically solve for the dynamic behavior of the pendulum for 100 seconds for the pendulum operating in vacuum. Sketch the behavior.
- (d) Numerically solve for the dynamic behavior of the pendulum for 100 seconds for the pendulum operating in air. Sketch the behavior.
- (e) Numerically solve for the dynamic behavior of the pendulum for 100 seconds for the pendulum operating in water. Sketch the behavior.
- (f) Determine the critical point of the system.
- (g) Construct the Jacobian of the system of ODEs and evaluate it at the critical point.
- (h) Report the eigenvalues of the Jacobian at the critical point for vacuum, air and water.
- (i) State the stability of the systems based on the solution of the ODEs and the eigenvalues. Sketch phase plot, if necessary.
- (j) extra credit: Is it possible to change the stability of the pendulum? Is it possible to lose all oscillatory behavior in the pendulum?